| Ref<br># | Hits | Search Query   | DBs   | Default<br>Operator | Plurals | Time Stamp       |
|----------|------|--|---|---------------------|---------|------------------|
| L1       | 136  | ((drive OR driving) ADJ wheel) WITH ((driven OR dependent OR auxiliary) ADJ wheel) WITH coaxial\$2 | US-PGPUB;<br>USPAT;<br>USOCR;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON      | 2007/06/21 14:00 |
| S1       | 4    | CN-1284177-\$.DID. OR<br>US-5551119-\$.DID. OR<br>WO-02075469-\$.DID.                              | US-PGPUB;<br>USPAT;<br>USOCR;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON      | 2007/06/20 12:36 |
| S2       | 2    | "6389329".PN.  | US-PGPUB;<br>USPAT;<br>USOCR;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON      | 2007/06/20 12:38 |
| S3       | 1    | EP-1368715-\$.DID.   | US-PGPUB;<br>USPAT;<br>USOCR;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON .    | 2007/06/20 12:39 |
| S4       | 2    | "5551119".pn.  | US-PGPUB;<br>USPAT;<br>USOCR;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON      | 2007/06/20 14:51 |
| S5       | 6    | ("5551119").URPN.  | USPAT   | OR                  | ON      | 2007/06/20 14:57 |
| S7       | 234  | 15/319.ccls. AND sensor  | USPAT   | OR                  | ON      | 2007/06/20 14:57 |
| S8       | 66   | 15/319.ccls. AND (sensor WITH wheel)   | USPAT   | OR                  | ON      | 2007/06/20 14:58 |
| S9       | 1    | 15/319.ccls. AND infared   | USPAT   | OR                  | ON      | 2007/06/20 15:37 |
| S10      | . 0  | wheel WITH infared WITH rotat\$3   | USPAT   | OR                  | ON      | 2007/06/20 15:37 |
| S11      | 7709 | wheel WITH sensor WITH rotat\$3  | USPAT   | OR                  | ON      | 2007/06/20 15:54 |
| S12      | 179  | wheel WITH sensor WITH rotat\$3<br>WITH emit\$4  | USPAT   | OR                  | ON      | 2007/06/20 15:40 |
| S13      | 11   | S12 AND motor AND robot  | USPAT   | OR                  | ON      | 2007/06/20 15:40 |
| S14      | 107  | wheel WITH sensor WITH robot   | USPAT   | OR                  | ON      | 2007/06/20 15:54 |
| S15      | 253  | (wheel WITH sensor WITH rotat\$3) AND robot  | USPAT   | OR                  | ON      | 2007/06/20 15:58 |

| S16 | . 0  | "wheel rotation sensor" AND infared                | USPAT   | OR | ON | 2007/06/20 15:59 |
|-----|------|--|---|----|----|------------------|
| S17 | 284  | "wheel rotation sensor"                            | USPAT   | OR | ON | 2007/06/20 16:00 |
| Ş18 | 25   | "wheel rotation sensor" AND robot                  | USPAT   | OR | ON | 2007/06/20 16:06 |
| S19 | 182  | (encoder WITH rota\$5 WITH wheel) AND robot        | USPAT   | OR | ON | 2007/06/20 16:07 |
| S20 | 695  | 901/1.ccls.  | US-PGPUB;<br>USPAT;<br>USOCR;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/06/20 16:20 |
| S21 | 29   | S20 AND (wheel WITH sens\$3<br>WITH rota\$4)       | US-PGPUB;<br>USPAT;<br>USOCR;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/06/20 16:22 |
| S22 | . 11 | 901/47.ccls. AND (wheel WITH sens\$3 WITH rota\$4) | US-PGPUB;<br>USPAT;<br>USOCR;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/06/20 16:24 |
| S23 | 7    | 901/46.ccls. AND (wheel WITH sens\$3 WITH rota\$4) | US-PGPUB;<br>USPAT;<br>USOCR;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/06/20 16:28 |
| S24 | 101  | 701/23.ccls. AND (wheel WITH sens\$3 WITH rota\$4) | US-PGPUB;<br>USPAT;<br>USOCR;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/06/21 07:52 |
| S25 | 156  | 180/65.1.ccls. AND (sensor WITH wheel)             | US-PGPUB;<br>USPAT;<br>USOCR;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/06/20 16:40 |
| S26 | 50   | 180/65.5.ccls. AND (sensor WITH rota\$4)           | US-PGPUB;<br>USPAT;<br>USOCR;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/06/21 07:49 |

|     |     | •   |   |      |    |                  |
|-----|-----|---|---|------|----|------------------|
| S27 | 24  | ("20030028993"   "5334762"   "5369347"   "6374155"   "6389329"   "6459955"   "6496754"   "6496755"   "6532404"   "6611120"   "6611738"   "6615108"   "6658325").PN. OR ("6748297"). URPN. | US-PGPUB;<br>USPAT;<br>USOCR                                      | OR   | ON | 2007/06/20 16:49 |
| S28 | 5   | ("5051906"   "5446356"  <br>"6496754"   "6748297").PN. OR<br>("6868307").URPN.  | US-PGPUB;<br>USPAT;<br>USOCR                                      | OR   | ON | 2007/06/20 16:51 |
| S29 | 121 | 180/65.1.ccls. AND (sensor WITH rota\$4)  | US-PGPUB;<br>USPAT;<br>USOCR;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/06/21 07:50 |
| S30 | 101 | 701/23.ccls. AND (wheel WITH sens\$3 WITH rota\$4)  | US-PGPUB;<br>USPAT;<br>USOCR;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/06/21 07:53 |
| S31 | 67  | S30 AND @ad<"20030811"  | US-PGPUB;<br>USPAT;<br>USOCR;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/06/21 13:58 |
| S32 | 12  | ("4119900"   "4515221"  <br>"4674048"   "4700302"  <br>"5032775"   "5479079"  <br>"5896488").PN. OR ("6038501").<br>URPN.   | US-PGPUB;<br>USPAT;<br>USOCR                                      | OR . | ON | 2007/06/21 08:01 |
| S33 | 10  | ("4632543"   "4855915"  <br>"5109566"   "5229941"  <br>"5234071"   "5461357").PN. OR<br>("5995883").URPN.   | US-PGPUB;<br>USPAT;<br>USOCR                                      | OR   | ON | 2007/06/21 08:08 |
| S34 | 25  | ("4530057"   "4600999"  <br>"4665489"   "4939650"  <br>"5218542"   "5377106"  <br>"5471385"   "5483453"  <br>"5764014"   "5765116").PN. OR<br>("5925080").URPN.                           | US-PGPUB;<br>USPAT;<br>USOCR                                      | OR   | ON | 2007/06/21 08:33 |
| S35 | 39  | robot AND (emit\$4 WITH receiv\$3 WITH wheel)   | US-PGPUB;<br>USPAT;<br>USOCR                                      | OR   | ON | 2007/06/21 08:33 |

6/21/2007 2:16:52 PM
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| S36 | 8    | ("4556940"   "4638445"  <br>"4817000"   "4937945"  <br>"4939650"   "4991126"  <br>"5042157"   "5233526").PŅ. OR<br>("5475600").URPN.  | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 08:48 |
|-----|------|---|------------------------------|----|----|------------------|
| S37 | 67   | 356/139.07.ccls.  | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 08:49 |
| S38 | 9    | 356/139.07.ccls. AND wheel  | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 08:54 |
| S39 | 140  | (wheel WITH (slot\$3 OR hole OR opening) WITH emit\$4 WITH receiv\$3)   | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 09:20 |
| S40 | 461  | (wheel WITH (slot\$3 OR hole OR opening) WITH sensor) AND ("180" OR "280").clas.  | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 09:25 |
| S41 | 253  | S40 NOT "throttle opening"  | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 09:26 |
| S42 | 461  | 15/319.ccls.  | USPAT                        | OR | ON | 2007/06/21 10:30 |
| S43 | . 12 | 15/319.ccls. AND coaxial  | USPAT                        | OR | ON | 2007/06/21 10:30 |
| S44 | 24   | ("20030028993"   "5334762"   "5369347"   "6374155"   "6389329"   "6459955"   "6496754"   "6496755"   "6532404"   "6611120"   "6611738"   "6615108"   "6658325").PN. OR ("6748297"). URPN. | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 10:35 |
| S45 | 1163 | robot AND vacuum AND coaxial  | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 10:39 |
| S46 | 31   | robot AND vacuum AND (coaxial WITH wheel)   | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 10:41 |
| S47 | 61   | robot\$2 AND vacuum AND<br>(coaxial\$2 WITH wheel)  | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 10:44 |
| S48 | 36   | (robot\$2 SAME vacuum) AND<br>(coaxial\$2 WITH wheel)   | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 10:50 |
| S49 | 57   | 901/1.ccls. AND vacuum  | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 10:50 |

6/21/2007 2:16:52 PM
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| S50 | 16 | ("4033068"   "4993912"  <br>"5248008"   "5293107"  <br>"5350033"   "5377106").PN. OR<br>("5515934").URPN.  | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 10:56 |
|-----|----|--|------------------------------|----|----|------------------|
| S51 | 1  | robot AND ("driving wheel" WITH "driven wheel" WITH coaxial)   | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 11:00 |
| S52 | 5  | robot AND ("driving wheel" WITH coaxial)   | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 11:01 |
| S53 | 7  | robot AND ("driven wheel" WITH coaxial)  | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 11:01 |
| S54 | 50 | ("0367420"   "2770074"   "3088157"   "3952361"   "3963096"   "4114711"   "4161793"   "4306329"   "4515235"   "4674048"   "4700427"   "4702718"   "4977639"   "5012886"   "5109566"   "5155684"   "5279672"   "5293955"   "5341540"   "5440216"   "5451014"   "5453931"   "5613261"   "5622236"   "5636402"   "5787545"   "5815880"   "5883861"   "5894621"   "5903124"   "5904196"   "5917442"   "5919078"   "5943009"   "5974347"   "5988306"   "5998953"   "5999866"   "6076025"   "6076226"   "6119057"   "6124694").PN. OR ("6941199").URPN. | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 11:28 |
| S55 | 30 | robot AND (sensor WITH "driven wheel")   | US-PGPUB;<br>USPAT;<br>USOCR | OR | ON | 2007/06/21 11:28 |